

Recall thm from last time:

$\mu, \nu \in \mathcal{P}(\mathbb{R}^n)$. $\int |x|^2 d\mu, d\nu < \infty$. $c(x, y) = \frac{1}{2}|x-y|^2$.

(1) $\pi_0 \in \Pi(\mu, \nu)$ is a minimizer to Kantorovitch iff $y \in \partial\varphi(x)$ for π -a.e. (x, y) .

(2) If $\mu \ll \text{dm}$ then $\exists!$ optimal π_0 . s.t. $\pi_0 = (\text{id} \times \nabla\varphi)_\# \mu$.
for some convex φ .

(3) If $\nu \ll \text{dm}$, then the two optimal maps are inverse to each other (in the sense of a.e.)

$$\mu \xrightarrow{\nabla\varphi} \nu$$

$$\text{then } \nu \xrightarrow{\nabla\varphi^*} \mu$$

$\varphi^* =$ Legendre transform of φ

$$\text{i.e. } \varphi^*(y) = \sup_x (x \cdot y - \varphi(x)).$$

Brenier's polar factorization thm,

$\Omega \subseteq \mathbb{R}^n$ bdd subset, $m(\Omega) > 0$. $h: \Omega \rightarrow \mathbb{R}^n \in L^2$. s.t.

$\forall N \subseteq \mathbb{R}^n, m(N), m(h^{-1}(N)) = 0$. (non degenerate condition).

Then \exists convex function. s.t. $h = \nabla \varphi \circ S$, where φ is convex. &
 $S: \Omega \rightarrow \Omega$ measure preserving
 $m(S^{-1}(A)) = m(A)$.

Moreover, this decomposition is unique. Also

$$\|S-h\|_{L^2} = \inf_{\sigma: \Omega \rightarrow \Omega} \|\sigma-h\|_{L^2}$$

measure preserving

proof (may be done later) follows from applying the previous thm to: $\mathbb{1}/\Omega, h_{\#}(\mathbb{1}/\Omega)$
non-degenerate condition $\Rightarrow h_{\#}(\mathbb{1}/\Omega) \ll \mathbb{1}$.

Why called polar factorization thm?

Recall the following result from linear algebra:

Let $M \in M_{n \times n}(\mathbb{R}^n)$, then $\exists O \in O_n(\mathbb{R})$ & $S \in S_n^+(\mathbb{R})$ s.t. $M = S \cdot O$.

Moreover, such O can be characterized as:

$$MO^{-1} \in S_n^+(\mathbb{R}) \iff \|M - O\|_{HS}^2 = \inf_{\tilde{O} \in O_n(\mathbb{R})} \|M - \tilde{O}\|_{HS}^2.$$

If M is invertible, then S & O is unique. $HS = \text{Hilbert Schmidt norm}$.

Relation between this p.f & Brenier's p.f:

$\Omega = B_1(0)$, $h: \Omega \rightarrow \mathbb{R}^n$, $hx = M \cdot x$. h non-degenerate $\iff M$ invertible.
then $h = \underline{\nabla} \varphi \circ g$. (Since h is linear, can pretend $\nabla \varphi$ & g is linear
($\det g = 1$)).
 g linear. $\det g = 1$. $g(B_1(0)) \subseteq B_1(0) \Rightarrow g \in O_n(\mathbb{R})$.

Relation to Helmholtz decomposition:

$\Omega \subseteq \mathbb{R}^n$ smooth domain, \vec{w} a smooth v.f. then $\vec{w} = \vec{v} + \nabla\varphi$.

$$\operatorname{div} \vec{v} = 0, \quad \vec{v} \cdot \vec{n} = 0 \text{ on } \partial\Omega.$$

pf: Let h_t be the flow generated from \vec{w} . $\frac{dh_t}{dt} = \vec{w}(h_t)$.

Then apply Brenier's thm. $h_t = \nabla\varphi_t \circ S_t$. φ_t is convex

Assume everything is smooth.

$S_t: \Omega \rightarrow \Omega$
measure preserving map.

$$\vec{w} = \left. \frac{dh_t}{dt} \right|_{t=0} = \left. \frac{d}{dt} (\nabla\varphi_t \circ S_t) \right|_{t=0} = \left. \nabla \frac{d\varphi_t}{dt} \circ S_t \right|_{t=0}$$

Since at $t=0$, $D^2\varphi_t = I$,
 $S_t = \operatorname{id}$.

$$+ D^2\varphi_t \cdot \left. \frac{dS_t}{dt} \right|_{t=0} = \left. \nabla \frac{d\varphi}{dt} \right|_{t=0} + \left. \frac{d^2\varphi}{dt^2} \right|_{t=0}$$

proof of Brenier's factorization thm:

pf: wlog, assume $m(\Omega)=1$. non-degenerate condition $\Rightarrow h_{\#}(\mathcal{L}/\Omega) \ll \mathcal{L}/\Omega$.
(check: $m(N)=0$. $h_{\#}(\mathcal{L}/\Omega) \subset N$
 $= m(h^{-1}(N))=0$)

Then \exists convex function φ & its Legendre transform φ^* s.t.

$$\nabla \varphi_{\#}(\mathcal{L}/\Omega) = h_{\#}(\mathcal{L}/\Omega) \quad \& \quad \mathcal{L}/\Omega = (\nabla \varphi^*)_{\#} h_{\#}(\mathcal{L}/\Omega)$$

So $S = \nabla \varphi^* \circ h$, then $S: \Omega \rightarrow \Omega$ measure preserving map.

& $h = \nabla \varphi \circ S$. (So we get the decomposition...)

Why $\|h - S\|_{L^2} = \inf_{\sigma \in \mathcal{S}(\Omega)} \|h - \sigma\|_{L^2}$?

First, you can write down the Kantorovich problem between $\mathcal{L}/\Omega, h_{\#}(\mathcal{L}/\Omega)$.
 $\inf \int |x - y|^2 d\gamma, \gamma \in \Pi(\mathcal{L}/\Omega, h_{\#}(\mathcal{L}/\Omega))$. Note $(\sigma \circ h)_{\#} \mathcal{L}/\Omega \in \Pi(\mathcal{L}/\Omega, h_{\#}(\mathcal{L}/\Omega))$.

Since $\nabla\varphi$ is the optimal map $\sigma \rightarrow \nabla\varphi\#(\mathbb{L}(\Omega)) = h\#(\mathbb{L}(\Omega))$.

$$\int_{\Omega} |x - \nabla\varphi(x)|^2 dx \leq \int |x - y|^2 d((\sigma \times h)\#\mathbb{L}(\Omega)) = \int_{\Omega} |\sigma(x) - h(x)|^2 dx$$

$$\int |x - y|^2 d((id \times \nabla\varphi)\#\mathbb{L}(\Omega))$$

$$\int |x - y|^2 d((\nabla\varphi_* \times id)\#h\#\mathbb{L}(\Omega))$$

$$\nabla\varphi_* \circ h = \Sigma$$

$$\int |x - y|^2 d((\Sigma \times h)\#\mathbb{L}(\Omega)) = \int_{\Omega} |\Sigma(x) - h(x)|^2 dx$$

Now we come to regularity question of optimal transport / MA eqn.

Special case: $\mu = f(x)dx$, $\nu = g(y)dy$, φ convex, $\nabla\varphi\#(\mu dx) = g dy$.

Eqn for φ (assume it's convex). $\nabla\varphi\#(f(x)dx) = g(y)dy$

Let $\zeta(y)$ be a test function.

$$\int \zeta(y)g(y)dy = \int \zeta(y) \frac{d(\nabla\varphi\#(f(x)dx))}{\|y = \nabla\varphi(x)\|} = \int \zeta(\nabla\varphi(x)) \underbrace{f(x)dx}_{\det D^2\varphi(x)}$$

$$\int \zeta(\nabla\varphi(x)) \underbrace{g(\nabla\varphi(x)) \det D^2\varphi(x)}_{g(\nabla\varphi(x)) \det D^2\varphi(x)} dx = \int \zeta(\nabla\varphi(x)) f(x) dx$$

Since ζ is arbitrary, $\underline{g(\nabla\varphi(x)) \det D^2\varphi(x) = f(x)}$. (*)

This motivates a possible definition of weak soln to (*).

We say a convex function φ solves (*) weakly, if

$$\nabla\varphi\#(f(x)dx) = g(y)dy. \quad (\text{Brenier solution}).$$

Other notions of weak solution:

(1) (Alexandrov solution)

φ convex, we can define its Hessian measure by

$$\mu \bar{E} = m(\partial \varphi(E)) \quad \partial \varphi(E) = \bigcup_{x \in E} \partial \varphi(x)$$

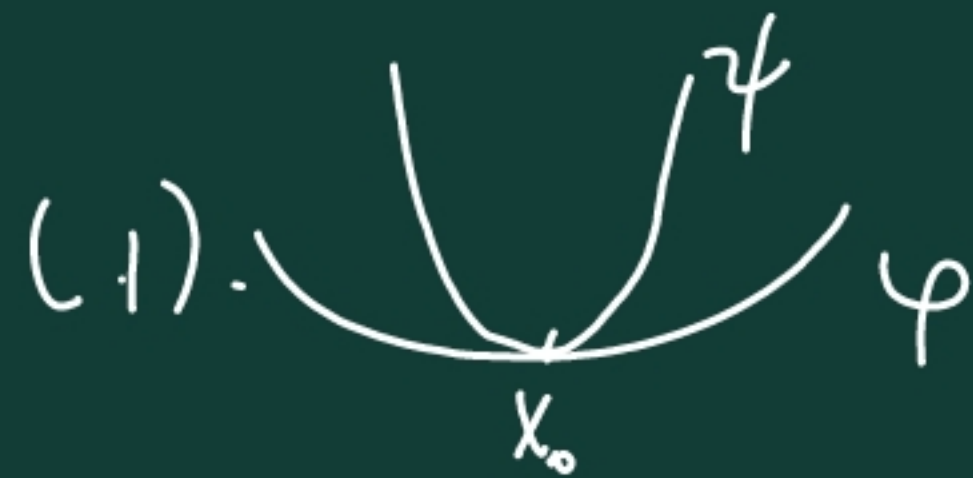
$$\partial \varphi(x) = \left\{ p \in \mathbb{R}^n : \varphi(y) \geq \varphi(x) + p \cdot (y-x) \right.$$

$$\left. \text{e.g.: } \varphi(x) = |x|, \partial \varphi(\{0\}) = [-1, 1] \cdot \forall y \in \mathbb{R}^n \right\}$$

we say $\det D^2 \varphi(x) = f(x, \varphi(x), \nabla \varphi(x))$ in the Alexandrov sense, if



(2) (viscosity solution)



$\forall C^2$ convex ψ ($\psi(x_0) = \varphi(x_0)$) $\mu = f(x, \varphi, \nabla \varphi)$
 $\det D^2 \psi(x_0) \geq f(x_0, \psi(x_0), \nabla \psi(x_0))$
 $\det D^2 \psi(x_0) \leq f(x_0, \psi(x_0), \nabla \psi(x_0))$

An example which is a Brenier soln but not Alexandrov.

$$\varphi(x_1, x_2) = \frac{1}{2}(x_1^2 + x_2^2) + |x_1|.$$



But φ solves $\det \bar{D}^2 \varphi = 1$ in Brenier sense.
 $\det_H \bar{D}^2 \varphi|_{B_1} = 1_{B_1} + \mathbb{1}_{H^1}|_{\left. \begin{array}{l} |x_1|=0 \\ |x_2|=1 \end{array} \right\}}$